



3.1

M60F SERIES

Bent-axial Piston Fixed Displacement Motor

M60F series bent-axial piston fixed displacement motor is used in an open or closed circuit. The bent-axial structure ensures a larger displacement and a more compact structure under the same volume.

Apply to open or close circuit

Size:	23	28	32	45	56	63	80	90	125*
Nominal pressure (bar):	400	400	400	400	400	400	400	400	400
Max pressure (bar):	450	450	450	450	450	450	450	450	450



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· M60F125*	17

Features

- Higher pressure and higher speed
- High activation efficiency
- Optimized power-weight ratio
- High torque and long service life
- Superior performance in low speed operation provides excellent controllability
- Suitable for engineering machinery and general industrial vehicles

Note: “*” indicates under development. Please stay tuned.

Technical Data

Feature		23	28	32	45	56	63	80	90	125
Max. Displacement (cc/rev)		23	28	32	44.9	56.1	63	79.8	90.5	125
Direction of rotation		Clockwise, Counter clockwise								
Rotation speed	Rated (rpm)	5500	6300	6300	5000	5000	4500	4000		
	Max. (rpm)	6000	6900	6900	5500	5500	5000	4400		
Rated pressure (bar)		400								
Max. pressure (bar)		450								
Casting pressure	Rated (bar)	6								
	Max. (bar) (Short-time peak pressure)	10								
Theoretical output torque (N·m)	@ $\Delta P=400$ bar	146	179	204	286	357	401	508	576	796
Max. Flow (L/min)	@ n_{nom}	138	177	202	225	281	315	359	407	500
Moment of inertia (kg·m ²)		0.0012	0.0012	0.0012	0.0033	0.0042	0.0042	0.0056	0.0058	0.0091
Weight (kg)		10.8	11.9	11.9	17	18	24.7	32.8		
Volume in the case (L)		0.2	0.2	0.2	0.6	0.45	0.65	1.1		
Oil viscosity (mm ² /s)		5 ~ 1600, Best range: 16~36								
Oil temperature (°C)		-25 ~ 103								
Oil cleanliness		ISO 4406 20/18/15								

Type Introduction

M60F	90	N	W	V	N4	D0	B	N	N	—	A
①	②	③	④	⑤	⑥	⑦	⑧	⑨	⑩		⑪

Product series

①	Bent-axial piston fixed displacement motor	M60F
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Size

②	Size	23	28	32	45	56	63	80	90	125
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Thread type of ports

③		23	28	32	45	56	63	80	90	125	Code
	UNC threads	●	●	●		●	●	●	●		A
	Metric threads	●	●	●	●	●	●	●	●	●	N
	G3/4 thread oil port	●	●	●							M

Direction of rotation

④	Clockwise, Counter clockwise	W
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Seals

⑤	FKM (Viton rubber: DIN ISO 1629)	V
	NBR (Nitrile rubber: DIN ISO 1629)	N

Mounting flange

⑥		23	28	32	45	56	63	80	90	125	Code
	100-4 ISO 3019-2	●	●	●							N3
	125-4 ISO 3019-2				●	●	●				N5
	127-4 SAE J744					●	●	●	●	●	N6
	140-4 ISO 3019-2							●	●		N4
	101.6-2 SAE J744 (Double hole)	●	●	●							

Type Introduction

Input shaft

	23	28	32	45	56	63	80	90	125	Code
W30×2×14×9g DIN 5480	●	●	●		●	●				D3
W35×2×16×9g DIN 5480				●	●	●				D0
W40×2×18×9g DIN 5480							●	●		D1
ANSI B92.1 21T-16/32DP							●	●		D2
W25×1.25×30×18×9g DIN 5480	●	●	●							D4
ASDI B92.1 14T-12/24DP					●	●				D6
ASDI B92.1 13T-16/32DP	●	●	●							D7
ASDI B92.1 23T-16/32DP									●	D8
Parallel key $\phi 32$ 10×8×60*							●	●		D5
Parallel key DIN 6885 $\phi 25$ 8×7×40	●	●	●							K1
Parallel key DIN 6885 $\phi 30$ 8×7×50					●	●				K2
Parallel key DIN 6885 $\phi 35$ 10×8×50					●	●				K3
Parallel key SAE J744 $\phi 31.75$ C7.94×38.1							●	●		K4

Note: The "D5" axis is a non-standard customized version. If you need to select, please contact Hengli.

Port position

	23	28	32	45	56	63	80	90	125	Code
⑧ Same side	●	●	●		●	●	●	●		B
Two sides	●	●	●	●	●	●	●	●	●	A

Control

⑨ Without	N
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Speed sensor

⑩	Without speed sensor	N
	With speed sensor (supply voltage 4.5~8VDC)	M
	With speed sensor (supply voltage 8~32VDC)	P
	Installation of reserved speed sensor	A

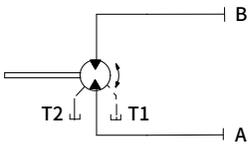
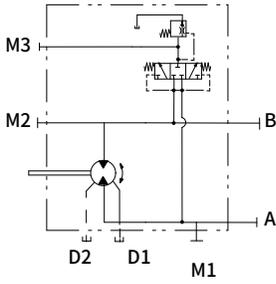
Note: Please refer to page 7/18 for specific parameters of the speed sensor.

Standard / special version

Standard version		N																												
⑪	Special version With flush valve	<table border="1"> <thead> <tr> <th>Flushing flow (L/min)</th> <th>Code</th> <th>Flushing flow (L/min)</th> <th>Code</th> </tr> </thead> <tbody> <tr> <td>3.5</td> <td>A</td> <td>20</td> <td>G</td> </tr> <tr> <td>5</td> <td>B</td> <td>25</td> <td>H</td> </tr> <tr> <td>8</td> <td>C</td> <td>30</td> <td>I</td> </tr> <tr> <td>10</td> <td>D</td> <td>35</td> <td>J</td> </tr> <tr> <td>14</td> <td>E</td> <td>40</td> <td>K</td> </tr> <tr> <td>17</td> <td>F</td> <td></td> <td></td> </tr> </tbody> </table>	Flushing flow (L/min)	Code	Flushing flow (L/min)	Code	3.5	A	20	G	5	B	25	H	8	C	30	I	10	D	35	J	14	E	40	K	17	F		
		Flushing flow (L/min)	Code	Flushing flow (L/min)	Code																									
		3.5	A	20	G																									
		5	B	25	H																									
		8	C	30	I																									
		10	D	35	J																									
		14	E	40	K																									
17	F																													
Opening pressure 16bar, differential pressure $\Delta P=25$ bar																														

Remark: ● = Available; ○ = On request

Principle

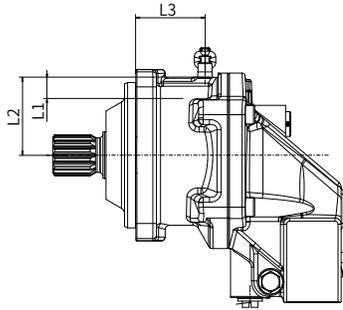


03

Speed sensor

The speed sensor is installed on the motor, which can record the motor speed and detect the direction of rotation of the motor.

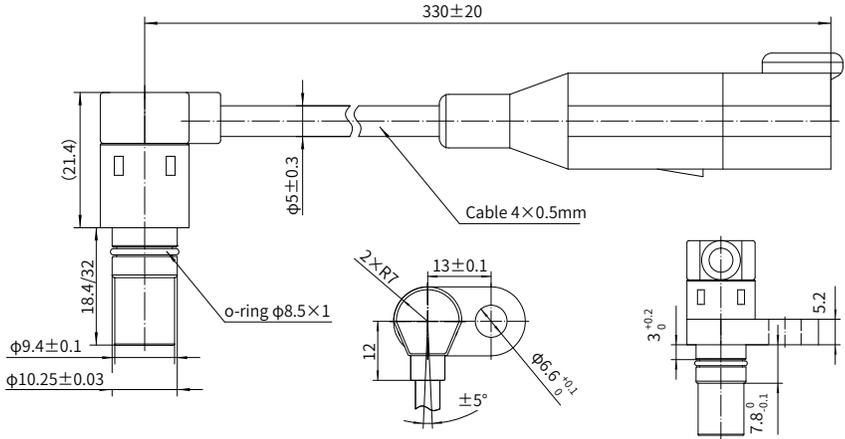
• M60V Installation diagram



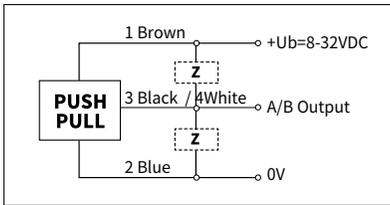
M60F Displacement cc/rev	23	28	32	56	63	80	90
Number of teeth in the speed ring	38	38	38	47	47	54	54
L1 (Probe length)mm	18.4	18.4	18.4	18.4	18.4	18.4	18.4
L2 (Sensor mounting surface to center axis) mm	57.9	57.9	57.9	69.9	69.9	75	75
L3 (Sensor to flange surface) mm	54.7	54.7	54.7	61.5	61.5	67.2	67.2
Gear module	2	2	2	2	2	2	2

Speed sensor

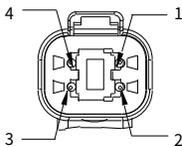
• Installation size



• Wiring diagram



Current consumption when unloaded	MAX.15mA
Maximum load current	50mA
Frequency range	0~20kHz
Temperature range for use	-40~125°C
Protection grade	IP67/IP69K
Output pulse count	Refer to the table for the number of teeth in the speed ring
Rotation recognition	Dual frequency output, 90° phase difference
Pressure resistance of measuring surface	10bar



DEUTSCH DT 04-4P	
PIN	function
1	VDC(8-32V)
2	GROUND
3*	Frequency signal A
4*	Frequency signal B

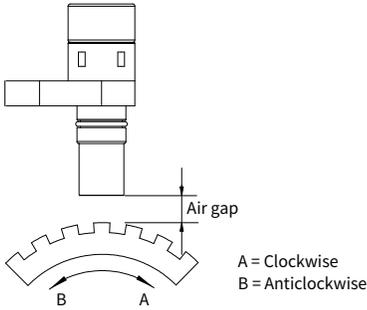
Note: “*” PIN3、 See 17/48 for the waveform diagram of output 4.

Speed sensor

· Output signal

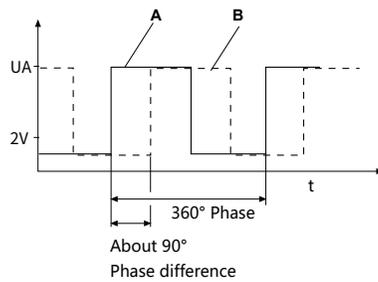
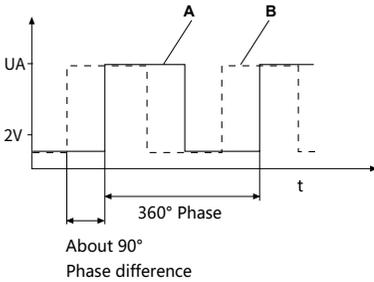
Reverse pulse output: $I_{max} \leq 50mA$

The frequency signal can be measured within the range of 0Hz to 20kHz.



Rotate clockwise to output waveform

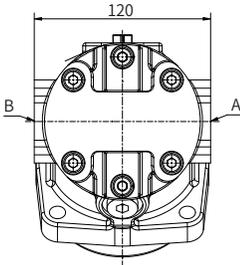
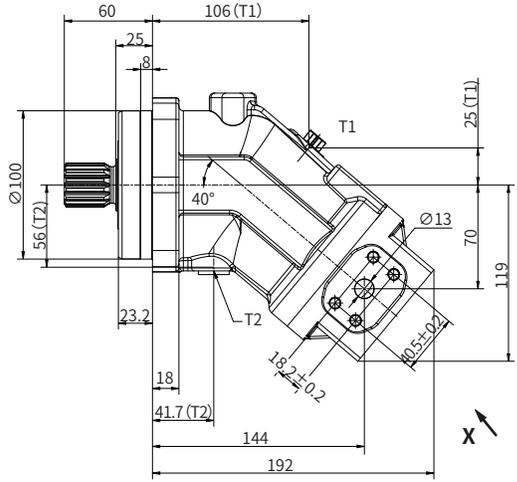
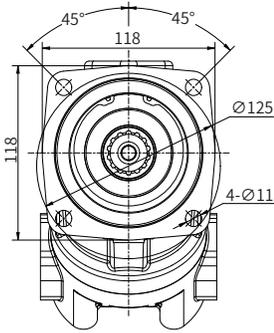
Rotate counterclockwise to output waveform



03

Installation size

M60F 23/28/32 Installation size



X View

03

Installation size

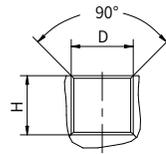
· M60F 23/28/32 Direction of rotation and oil flow direction

Installation	Rotation
Flow A → B	Clockwise
Flow B → A	Counter-clockwise

· M60F 23/28/32 Port details

	Port name	Port size and description	Tightening torque (N·m)
A、B	Inlet port and Delivery port	SAE J518 DIN 13 1/2" M12×1.75 (depth 17mm)	32
T1、T2	Case drain port	DIN 3852 M18×1.5 (depth 12mm)	55

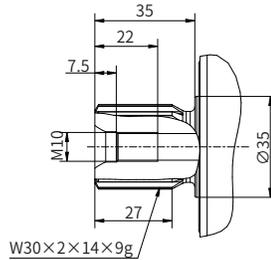
Port	H	D	M
T1	12	∅ 16	M16×1.5
T2	12	∅ 16	M16×1.5



03

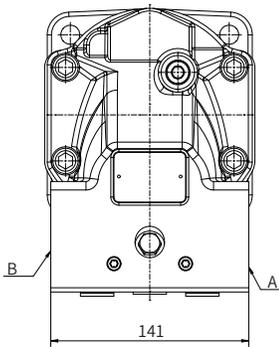
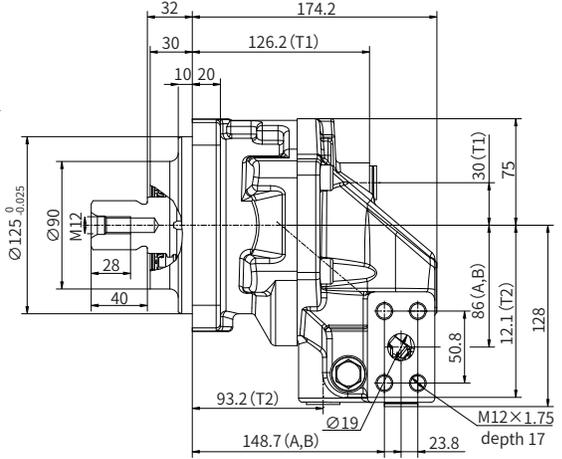
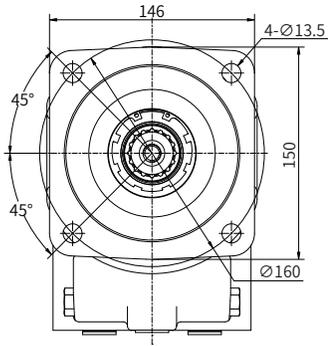
· M60F 23/28/32 Input shaft type

“D3” type shaft



Installation size

M60F 45 Installation size



03

Installation size

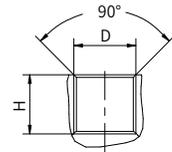
· M60F 45 Direction of rotation and oil flow direction

Installation	Rotation
Flow A → B	Clockwise
Flow B → A	Counter-clockwise

· M60F 45 Port details

	Port name	Port size and description	Tightening torque (N·m)
A, B	Inlet port and Delivery port	SAE J518 DIN 13 3/4" M12×1.75 (depth 17mm)	130
T1, T2	Case drain port	DIN 3852 M18×1.5 (depth 12mm)	60

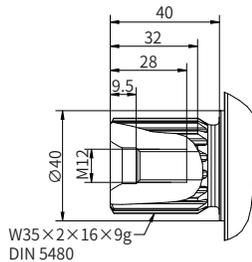
Port	H	D	M
T1	17	∅ 18	M18×1.5
T2	17	∅ 18	M18×1.5



03

· M60F45 Input shaft type

“D0” type shaft



Installation size

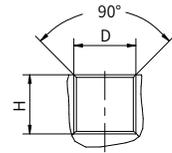
· M60F 56/63 Direction of rotation and oil flow direction

Installation	Rotation
Flow A → B	Clockwise
Flow B → A	Counter-clockwise

· M60F 56/63 Port details

	Port name	Port size and description	Tightening torque (N·m)
A、B	Inlet port and Delivery port	SAE J518 DIN 13 3/4" M12×1.75 (depth 17mm)	130
T1、T2	Case drain port	DIN 3852 M18×1.5 (depth 12mm)	60

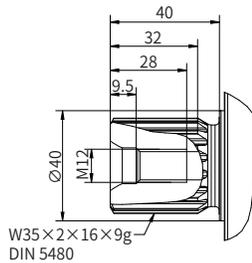
Port	H	D	M
T1	17	∅ 18	M18×1.5
T2	17	∅ 18	M18×1.5



03

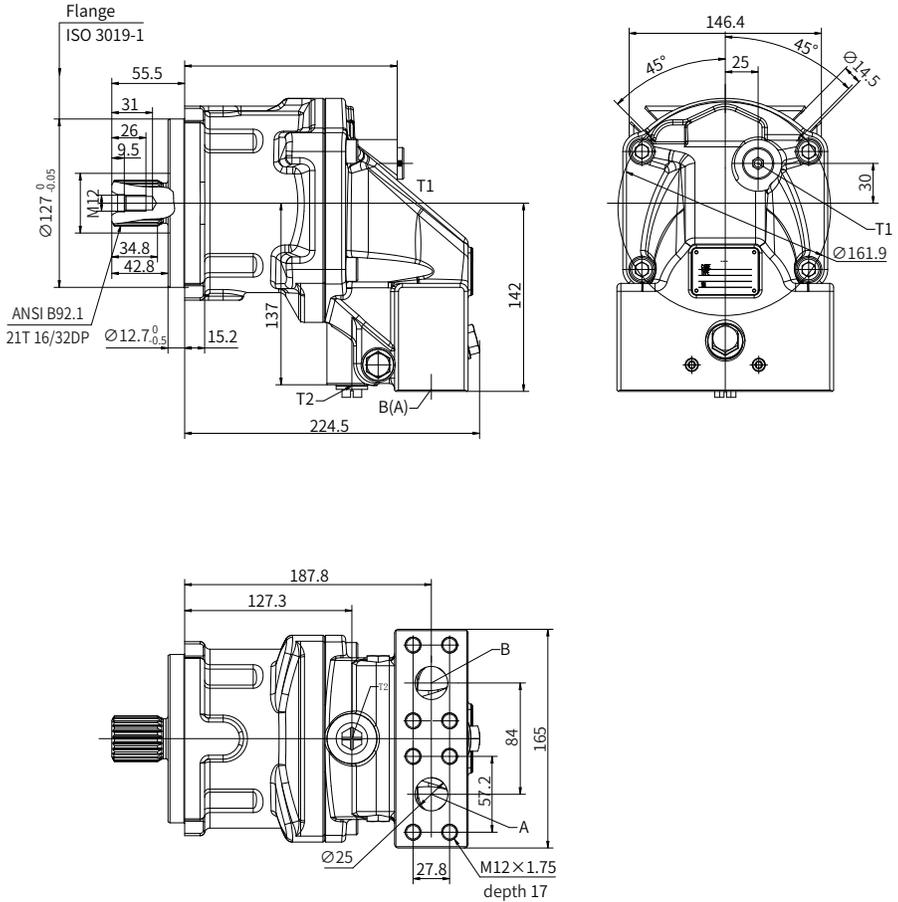
· M60F 56/63 Input shaft type

“D0” type shaft



Installation size

M60F 80/90 Installation size



03

Installation size

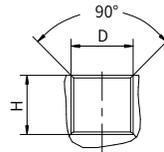
· M60F 80/90 Direction of rotation and oil flow direction

Installation	Rotation
Flow A → B	Clockwise
Flow B → A	Counter-clockwise

· M60F 80/90 Port details

	Port name	Port size and description	Tightening torque (N·m)
A, B	Inlet port and Delivery port	SAE J518 DIN 13 1" M12×1.75 (depth 17mm)	130
T1, T2	Case drain port	DIN 3852 M18×1.5 (depth 12mm)	60

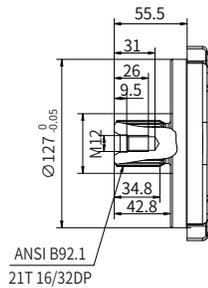
Port	H	D	M
T1	17	∅ 18	M18×1.5
T2	17	∅ 18	M18×1.5



03

· M60F 80/90 Input shaft type

“D2” type shaft



Installation size

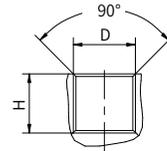
· M60F 125 Direction of rotation and oil flow direction

Installation	Rotation
Flow A → B	Clockwise
Flow B → A	Counter-clockwise

· M60F 125 Port details

	Port name	Port size and description
A, B	Inlet port and Delivery port	1 1/4 in M14×2.23 (depth 23mm)
TI, T2	Case drain port	DIN 3852 M18×1.5 (depth 12mm)

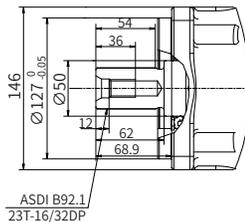
Port	H	D	M
T1	17	∅ 18	M18×1.5
T2	17	∅ 18	M18×1.5



03

· M60F 125 Input shaft type

“D8” type shaft



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